

## 國立臺北科技大學 109 學年度碩士班招生考試

系所組別：1302 車輛工程系碩士班

## 第二節 自動控制 試題 (選考)

第 1 頁 共 1 頁

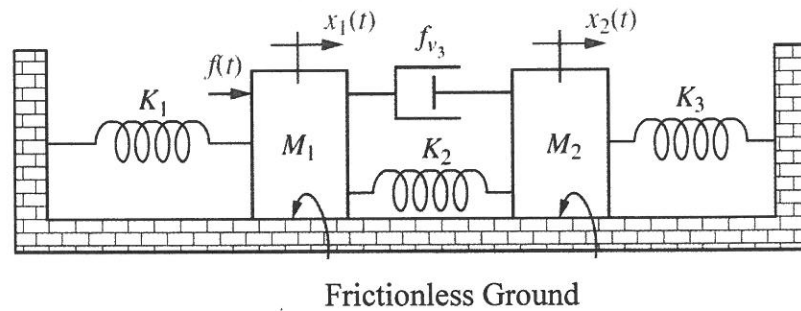
**注意事項：**

1. 本試題共 5 題，每題 20 分，共 100 分。
2. 不必抄題，作答時請將試題題號及答案依照順序寫在答案卷上。
3. 全部答案均須在答案卷之答案欄內作答，否則不予計分。

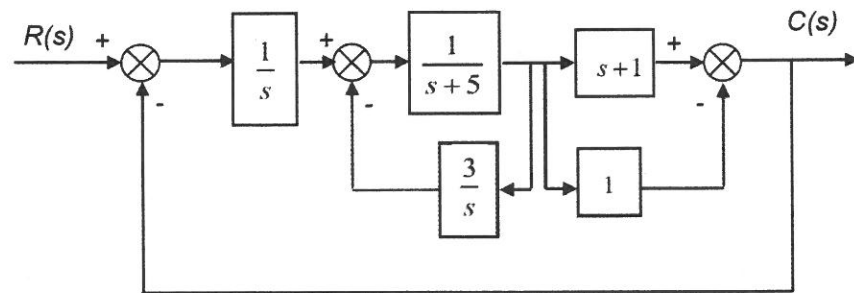
1. For the following mechanical system, find the transfer function

a. Find the transfer function  $G(s) = \frac{X_2(s)}{F(s)}$ . (10%)

b. Find the state equations representation of the system. (10%)



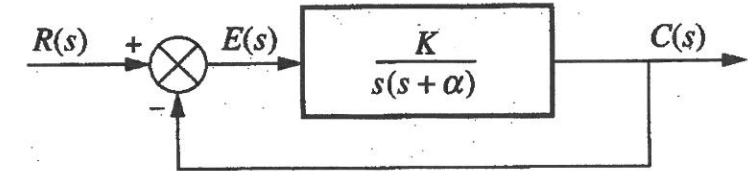
2.

a. For the above system, find the transfer function  $T(s) = \frac{C(s)}{R(s)}$  (10%)

b. Convert the block diagram into the signal flow graph representation. (5%)

c. Use Mason's gain formula to find the transfer function  $T(s) = \frac{C(s)}{R(s)}$  (5%)

3. For the following system

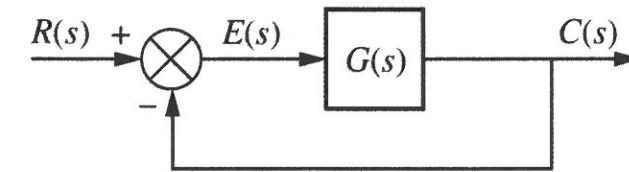
a. Find  $K$  and  $\alpha$  to yield a settling time of 0.1 second and a 20% overshoot. (10%)b. Find the time response  $c(t)$  when the input  $R(s) = \frac{1}{s}$ . (10%)

4. For the system :

$$\frac{Y(s)}{R(s)} = \frac{(s+1)}{s^3 + 2s^2 + s + K}$$

a. By Routh-Hurwitz criterion, find the range of  $K$  for which the system is stable. (10%)b. When the input  $R(s) = \frac{1}{s}$ , determine the steady-state error  $e_{ss} = \lim_{t \rightarrow \infty} e(t)$ . (10%)(Note:  $e(t) = r(t) - y(t)$ ).

5. Consider the unity feedback system



with the forward transfer function

$$G(s) = \frac{K}{s(s+3)(s+10)}$$

The system is operating at 20% overshoot. Design a compensator to decrease the settling time by a factor of 2 without affecting the percent overshoot and do the following:

a. Evaluate the uncompensated system's dominant poles, gain, and settling time. (10%)

b. Evaluate the compensated system's dominant poles and settling time. (10%)