國立高雄應用科技大學 九十七學年度碩士班招生考試 機械與精密工程研究所(乙組)

自動控制

試題 共3頁第1頁

注意:a. 本試題共5題, 每題20分, 共100分。

- b. 作答時不必抄題。
- C. 考生作答前請詳閱答案卷之考生注意事項。
- 1. Consider the following block diagram of a system, find the closed-loop transfer function C(s)/R(s). (20%)

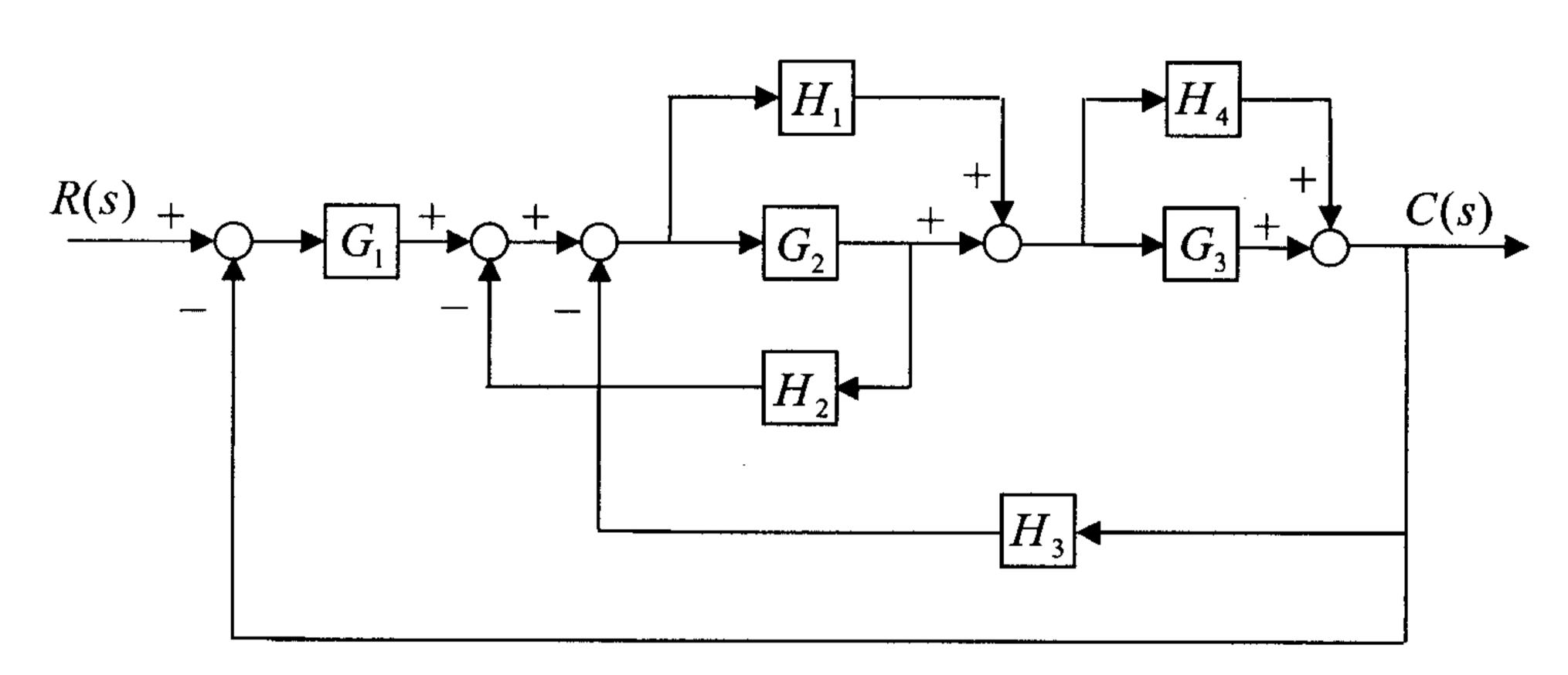
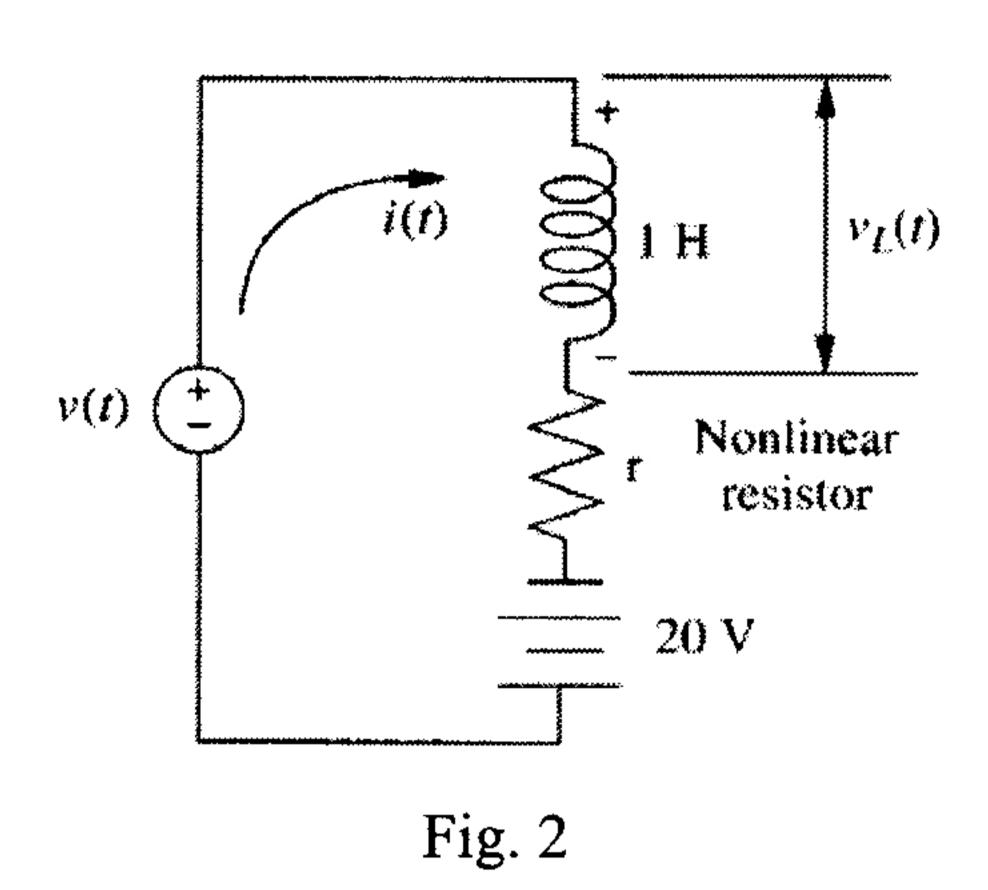


Fig. 1

- 2. Consider the electric network shown in Fig. 2, which contains a nonlinear resistor whose voltage-current relationship is defined by $i_r(t) = 5e^{0.2v_r(t)}$, where $i_r(t)$ and $v_r(t)$ are the resistor current and voltage, respectively.
 - (1) Calculate the resistor current at the equilibrium state (as v(t) = 0). (5%)
 - (2) Find the transfer function, $V_L(s)/V(s)$, for the electric network system. (15%)



3. Fig. 3 shows a mechanical vibratory system. When 2 lb force (step input) is applied to the system. In the Fig. 3, m, b, and k are mass, viscous friction coefficient, and spring constant, respectively. Determine m, b, and k of the system such that the system has maximum overshoot 0.01 at time 2sec and the steasy-state displacement $x(\infty)$ equals to 0.2. (20%)

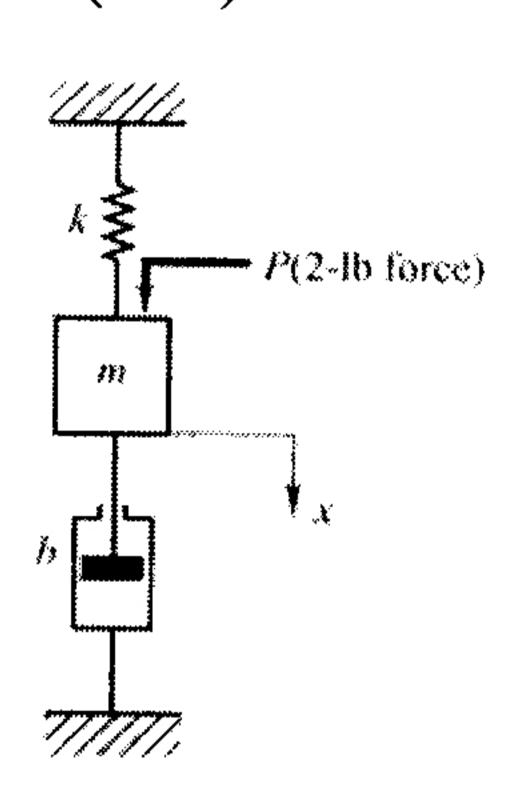


Fig. 3

- 4. Consider a system, as shown in Fig. 4(a).
 - (1) Derive the transfer function C(s)/R(s). (8%)
 - (2) Find the range of K for which the system is stable. (6%)
 - (3) Find the value of K that will place the closed-loop poles as shown in Fig. 4(b). (6%)

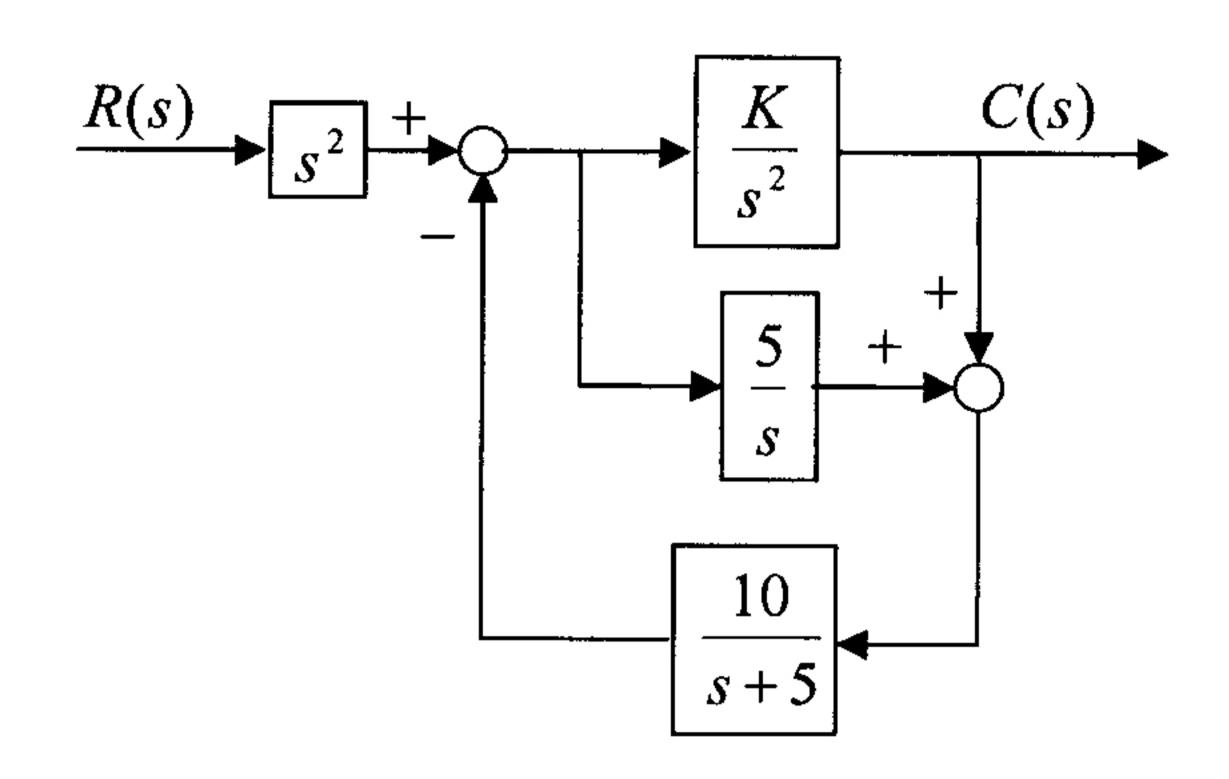


Fig. 4(a) $\begin{array}{c}
j\omega \\
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5. Consider the system of Fig. 5. Design the value of K so that for a ramp input of 20t, there will be a 0.02 error in the steady state. (20%)

Fig. 4(b)

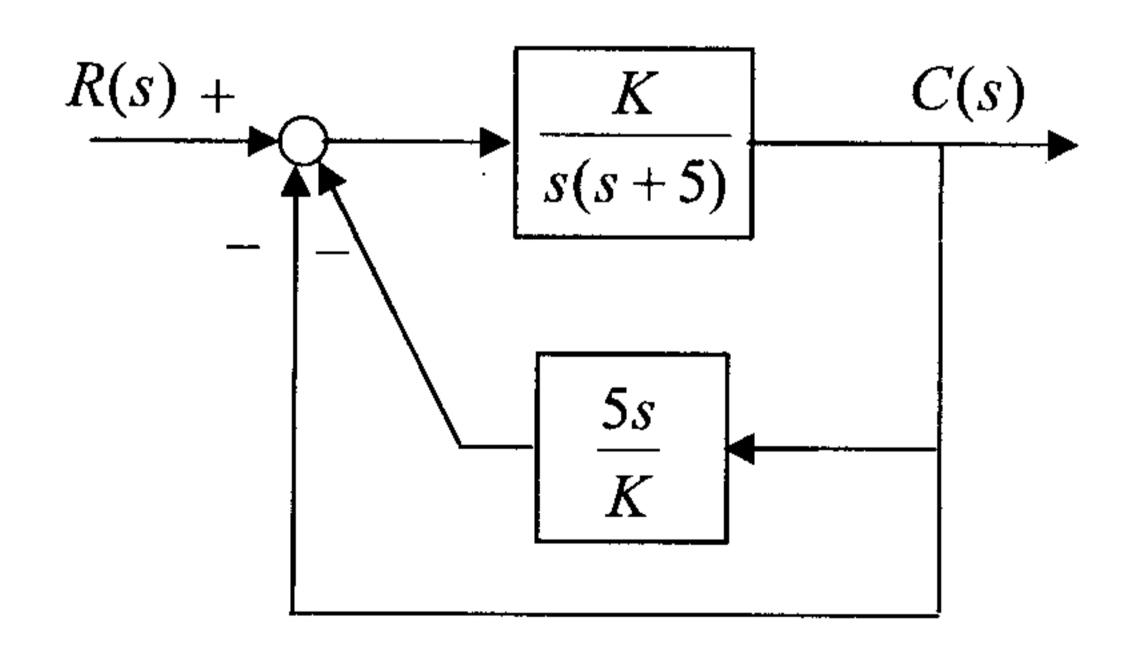


Fig. 5