

# 國立中央大學 108 學年度碩士班考試入學試題

共 5 頁 第 1 頁

所別：資工類

科目：資料結構與演算法

本科考試禁用計算器

\*請在答案卷(卡)內作答

單選題 25% (每題 5 分，答錯倒扣一分)，倒扣到該大題 0 分為止。

1. Suppose that the following list is the result of the first partition step of quick sort.

12 9 1 13 19 24 22 20

Which of the following statements is correct about the partition step?

- (A) The pivot could have been either 13 or 19.
  - (B) The pivot must be 13.
  - (C) Both 13 and 19 are pivots in the first partition.
  - (D) Neither 13 nor 19 could have been the pivot.
  - (E) None of the above
2. Build a *binary search tree* for the input sequence 9, 4, 8, 7, 20, 15, 14, 3, 10. It is assumed that the tree root is on level 1.
- (A) There are five levels in the tree.
  - (B) 20 is on level 3.
  - (C) 7 and 10 have the same father.
  - (D) The left subtree of 20 has 1 node.
  - (E) None of the above
3. Which of the following tree is a legal max-heap?
- (A) A tree with level-order traversal sequence {67, 45, 19, 22, 43, 16}
  - (B) A tree with level-order traversal sequence {67, 43, 19, 22, 45, 16}
  - (C) A tree with level-order traversal sequence {14, 18, 27, 19, 63, 48}
  - (D) A tree with level-order traversal sequence {45, 22, 67, 8, 34, 52}
  - (E) None of the above.

The following procedure recursively generates all the permutations of list[i] to list[n].

```
void perm(char *list, int i, int n)
{
    int j, temp;
    if (i==n) { /* print the newly generated permutation */
        for (j=0; j<=n; j++)
            printf("%c", list[j]);
        printf(" ");
    }
    else { /* generate permutations recursively */
        for (j=i; j<=n; j++) {
            (B1)
            (B2)
            swap(list[i], list[j], temp);
        }
    }
}
```

4. Blank (B1) in the algorithm above should be
- (A) swap(list[i+1], list[j], temp)
  - (B) swap(list[i], list[j], temp)
  - (C) swap(list[i], list[j+1], temp)
  - (D) swap(list[i+1], list[j+1], temp)
  - (E) None of the above

參考用

注意：背面有試題

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共 5 頁 第 2 頁

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\*請在答案卷(卡)內作答

5. Blank (B2) in the algorithm above should be
- (A) perm(list, i+1, n)
  - (B) perm(list, i, n)
  - (C) perm(list, j, n)
  - (D) perm(list, j+1, n)
  - (E) None of the above

複選題 35% (每題 5 分，答錯每題倒扣 1 分)，倒扣到該大題 0 分為止。

6. Consider an empty hash table with 10 buckets and each bucket has 2 slots. Suppose that the hash function is  $h(n) = n \% 10$ , and the following numbers, 6 16 22 45 54 25 7 75 5 108, are sequentially inserted into the hash table. Which of the following statements are true?
- (A) if linear probing is adopted to handle overflow, the summation of the numbers in the full buckets of the hash table is 287.
  - (B) if linear probing is adopted to handle overflow, the summation of the numbers in the full buckets of the hash table is 172.
  - (C) if quadratic probing is adopted to handle overflow, the summation of the numbers in the full buckets of the hash table is 221.
  - (D) Compared with quadratic probing, linear probing requires fewer bucket accesses (in average).
  - (E) None of the above.
7. A hash function maps a key into a bucket in the hash table. Which of the following statements is true?
- (A) A division hash function with divisor  $D = 7^r$ , where  $r$  is an integer, may result in serious collision.
  - (B) Compared with hash chaining, open addressing requires fewer bucket accesses (in average)
  - (C) When hash chaining is used to resolve overflows, the search for a key involves comparison with keys that have different hash values.
  - (D) In dynamic hashing, data buckets grows or shrinks (added or removed dynamically) as the records increases or decreases.
  - (E) None of the above.
8. Consider the problem of solving all-pairs shortest-paths on a weighted directed graph  $G = (V, E)$ . A famous dynamic programming algorithm gives a recursive formula to compute  $d^{(k)}[i, j]$ , the length of a shortest path from  $i$  to  $j$  using only vertices with indices not greater than  $k$ . Here it is assumed that the vertex set  $V = \{1, 2, \dots, n\}$  if the given graph contains  $n$  vertices. Now if the given graph has 5 vertices and edges: (1,4,-5), (1,5,2), (2,1,6), (3,1,1), (3,2,7), (4,3,4), (5,2,-4), (5,3,3), (5,4,8), where each triple  $(i, j, t)$  represents there is an edge directed from  $i$  to  $j$  with weight  $t$ . Then, after the execution of the algorithm, each term  $d^{(k)}[i, j]$  will be computed correctly. For the following items, choose the correct one(s):
- (A)  $d^{(2)}[5,1] = 2$
  - (B)  $d^{(2)}[5,4] = -3$
  - (C)  $d^{(3)}[4,1] = 4$
  - (D)  $d^{(3)}[4,2] = 11$
  - (E)  $d^{(3)}[4,5] = 6$
9. Follow the previous question. Choose the correct item(s):
- (A)  $d^{(4)}[1,2] = 7$
  - (B)  $d^{(4)}[1,3] = -1$
  - (C)  $d^{(5)}[1,2] = -2$
  - (D)  $d^{(5)}[3,2] = -2$
  - (E)  $d^{(5)}[4,2] = 3$

注意：背面有試題



# 國立中央大學 108 學年度碩士班考試入學試題

所別： 資工類

共 5 頁 第 3 頁

科目： 資料結構與演算法

本科考試禁用計算器

\*請在答案卷(卡)內作答

10. Given a weighted undirected graph  $G = (V, E)$ , let  $\delta[u, v]$  denote the distance (the length of a shortest path) from vertex  $u$  to vertex  $v$ . A path  $[v_1, v_2, \dots, v_k]$  is said to be a *progress path*, if  $\delta[v_i, v_k] > \delta[v_{i+1}, v_k]$  for  $1 \leq i < k$ . For example, consider the graph with vertex set  $\{1, 2, 3, 4\}$  and edge set:  $(1,2,2), (2,4,1), (3,1,2), (3,4,2), (1,4,3)$ , where each triple  $(i, j, t)$  represents there is an undirected edge between  $i$  and  $j$  with weight  $t$ . Then, in this graph, there are totally 2 shortest paths from 1 to 4 (i.e.  $[1,2,4]$  and  $[1,4]$ ) and there are 3 progress paths from 1 to 4 (they are  $[1,2,4]$ ,  $[1,4]$  and  $[1,3,4]$ ). Now consider another graph with vertex set  $\{a, b, c, d, e, f, g, h\}$  and edge set:  $(a,b,3), (a,c,1), (b,c,1), (b,e,5), (b,f,4), (c,d,9), (d,e,5), (d,g,3), (e,f,2), (e,g,2), (f,h,7), (g,h,4)$ . According to this graph, choose the correct item(s):
- (A)  $\delta[a,h] = 13$   
 (B)  $\delta[b,h] = 12$   
 (C)  $\delta[d,h] = 6$   
 (D)  $\delta[e,h] = 5$   
 (E)  $\delta[f,h] = 7$
11. Follow the previous question. Choose the correct item(s):
- (A)  $[b,c,d,g,h]$  is a progress path.  
 (B)  $[b,e,d,g,h]$  is a progress path.  
 (C)  $[b,e,f,h]$  is a progress path.  
 (D)  $[a,b,f,h]$  is a progress path.  
 (E)  $[a,b,e,g,h]$  is a progress path.
12. Follow the previous question. Choose the correct item(s):
- (A) There is totally 1 progress path from  $e$  to  $h$ .  
 (B) There are totally 9 progress paths from  $a$  to  $h$ .  
 (C) There is totally 1 progress path from  $f$  to  $h$ .  
 (D) There are totally 3 progress paths from  $b$  to  $h$ .  
 (E) There are totally 5 progress paths from  $c$  to  $h$ .

## 問答題 40%

1. A divide-and-conquer algorithm solves a problem directly if the problem is small. If the problem is large, it is first **divided** into two or more parts called subproblems. Each subproblem is then recursively solved (**conquered**) in the same manner. Afterwards, the solutions to the subproblems are combined (**merged**) into a solution to the original problem. The merge sort algorithm is a well-known example following the divide-and-conquer paradigm. The key operation of the merge sort algorithm is the merging of two sorted sequences. To perform the merging, we use an auxiliary procedure  $MERGE(A, p, q, r)$ , where  $A$  is an array and  $p, q$ , and  $r$  are indices numbering elements of the array such that  $p \leq q < r$ . The procedure assumes that the subarrays  $A[p \dots q]$  and  $A[q + 1 \dots r]$  are in sorted order. It merges them to form a single sorted subarray that replaces the current subarray  $A[p \dots r]$ . The pseudo code of the  $MERGE$  operation is shown below. Based on the operation, we can design the merge sort algorithm easily.
- (a) Write a detailed divide-and-conquer merge sort algorithm using the  $MERGE$  operation. Note that the algorithm **MUST** include well-described input and output. (9%)
- (b) Analyze the time complexity of the merge sort algorithm with the big-O notation. (8%)

$MERGE(A, p, q, r)$

**Input:**

$A$ : an array of elements;

$p, q, r$ : indices of  $A$ , where  $p \leq q < r$ , and the subarrays  $A[p \dots q]$  and  $A[q + 1 \dots r]$  are in sorted order (from small to large).

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**Output:**

$A$ : an array of elements, where the subarray  $A[p..r]$  is in sorted order (from small to large)

1.  $n_1 \leftarrow q - p + 1$
  2.  $n_2 \leftarrow r - q$
  3. create arrays  $L[1..n_1 + 1]$  and  $R[1..n_2 + 1]$
  4. for  $i \leftarrow 1$  to  $n_1$
  5.     do  $L[i] \leftarrow A[p + i - 1]$
  6. for  $j \leftarrow 1$  to  $n_2$
  7.     do  $R[j] \leftarrow A[q + j]$
  8.  $L[n_1 + 1] \leftarrow \infty$
  9.  $R[n_2 + 1] \leftarrow \infty$
  10.  $i \leftarrow 1$
  11.  $j \leftarrow 1$
  12. for  $k \leftarrow p$  to  $r$
  13.     do if  $L[i] \leq R[j]$
  14.         then  $A[k] \leftarrow L[i]$
  15.              $i \leftarrow i + 1$
  16.         else  $A[k] \leftarrow R[j]$
  17.              $j \leftarrow j + 1$
2. Given a chain  $\langle A_1, \dots, A_n \rangle$  of  $n$  matrices, where matrix  $A_i, i=1, \dots, n$ , has dimension  $p_{i-1} \times p_i$ , the matrix-chain multiplication problem is to fully parenthesize the product  $A_1 \dots A_n$  in a way that minimizes the number of scalar multiplications. We can use the dynamic programming strategy to solve the matrix-chain multiplication problem as follows. Define  $m[i, j]$  to be the minimum number of scalar multiplications needed to compute the matrix product  $A_i \dots A_j, i \leq j$ . Since we know the value of  $m[i, j]$  for  $i=j$ , we can then calculate  $m[1, n]$  in a bottom-up manner as the minimum number of scalar multiplications for the product  $A_1 \dots A_n$  by a recursive form of  $m[i, j]$ .

**Write down the recursive form of  $m[i, j]$ . (8%)**

3. Below is the algorithm AllPairCost which computes the shortest distances between all pairs of vertices  $i, j$ , where  $i \neq j$ . Formally, given distances of edges in graph  $G$ , determine the shortest distances between all pairs of vertices in  $G$ . Note that the distance of an arbitrary edge in  $G$  is non-negative.

(a) Blanks (B3) and (B4) in the algorithm below should be \_\_\_\_\_ (4%)

(b) Blank (B5) in the algorithm below should be \_\_\_\_\_ (3%)

**Algorithm AllPairCost**

**Input:** a two dimensional array  $C$ , where  $C[i][j]$  denotes the distance of directed edge  $(i, j)$  (i.e., the edge from vertex  $i$  to vertex  $j$ ).

**Output:** a two dimensional array  $D$ , where  $D[i][j]$  denotes the shortest distance from vertex  $i$  to vertex  $j$ .

```

1: int  $i, j, k$ ;
2: for ( $i=0; i < n; i++$ )
3:   for ( $j=0; j < n; j++$ )
4:     _____ (B5);
5:   for ( $k=0; k < n; k++$ )
6:     for ( $i=0; i < n; j++$ )
7:       for ( $j=0; j < n; j++$ )
8:         if (_____ (B3))
9:           _____ (B4);
    
```

參考用

注意：背面有試題

國立中央大學 108 學年度碩士班考試入學試題

所別： 資工類

共5頁 第5頁

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本科考試禁用計算器

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4. Suppose that array  $A[1:n]$  maintains a binary tree. For a binary tree node stored in  $A[i]$ , its two children (if exist) are stored in  $A[2i]$  and  $A[2i+1]$ , respectively. The program below aims to complete the following two tasks
- adjust array A to establish a max heap, and
  - apply heap sort on the max heap built in (1) in nondecreasing order.
- (a) Blank (B6) in the program below should be \_\_\_\_\_ (4%)
- (b) Blank (B7) in the program below should be \_\_\_\_\_ (4%)

```
void adjust (int A[], int root, int n)
{
    int child, rootkey;
    int temp;
    temp = A[root];
    rootkey = A[root];
    child = 2* root;
    while ( child <=n ) {
        if (( child <=n ) && ( A[child] < A[child+1] ))
            child ++;
        if ( rootkey > A[child] )
            break;
        else {
            _____ (B6) _____;
            child *=2; }
    }
    _____ (B7) _____;
}

void heapsort (int A[], int n)
{ /* perform a heap sort on A[1:n] */
    int i, j;
    int temp;
    for (i=n/2; i>0; i++) /* adjust the binary tree to establish the max heap */
        adjust (A, i, n);
    for (i=n-1; i>0; i--) { /* heap sort */
        swap( A[i], A[i+1], temp); /* exchange A[i] and A[i+1] */
        adjust(A, i, i); }
}
```

參考用