編號: 138

國立成功大學 107 學年度碩士班招生考試試題

系 所:航空太空工程學系

考試科目:自動控制

考試日期:0205,節次:1

第1頁,共2頁

※ 考生請注意:本試題不可使用計算機。 請於答案卷(卡)作答,於本試題紙上作答者,不予計分。

- 1. Consider the feedback control system shown in Fig.1, where $G(s) = \frac{5}{s^2 + 6s + 8}$
 - (a). (10%) Design a controller kC(s) to achieve the following requirements
 - (1). Zero steady state error to a step reference R(s)
 - (2). Settling time (2% error) = 2 s.
 - (3). damping ratio=0.5.
 - (b). (5%) Determine poles and zeros of the closed-loop system obtained in part (a).
 - (c). (10%) Plot root locus of the system with C(s) obtained in part (a) with k > 0.

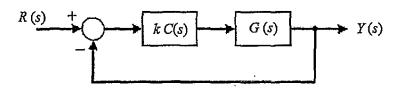


Fig.1 Block diagram of a closed-loop control system.

- 2. Consider a unity feedback system shown in Fig.2, where $KG(s) = \frac{K}{s(s^2 + 52s + 100)}$,
 - (a). (10%) For K = 1000, plot the Bode plot of G(s) and determine phase margin, gain margin, phase crossover frequency, gain crossover frequency.
 - (b). (7%) For K = 1000, plot the Nyquist plot of G(s) and determine the upper bound of K for system stability.
 - (c). (8%) Determine K such that the system has a phase margin of 45 degree.

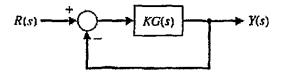


Fig2. A unity feedback system.

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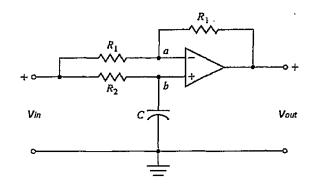
系 所:航空太空工程學系

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第2頁,共2頁

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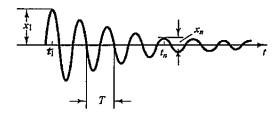
- 3. An operational amplifier circuit that can serve as a filter circuit is shown as follows.
- (a). Determine the transfer function of the circuit $V_{out}(s)/V_{in}(s)$, assuming an ideal op-amp (10%).
- (b). Find $v_{out}(t)$ when the input is $v_{in}(t) = At$, where $t \ge 0$ (10%).
- (c). Can we use the filter to attenuate the noise that appears in the input $v_{in}(t)$ (5%)? Please explain the reason (5%).



4. An oscillator is designed as a standard 2nd order system

$$G(s) = \frac{\omega_n^2}{s^2 + 2\zeta \omega_n s + \omega_n^2}$$

where the response is shown as follows. Please calculate the damping ratio, which is represented in terms of x_1 , x_n and n. (10%)



- 5. Consider the satellite attitude control system shown in Figure 5(a).
- (a). Please find the steady state error when R(s) is a step input. (5%)
- (b). Consider Figure 5(b), can we design a proper K_h to achieve a desired nature frequency? Please explain why and how? (5%)

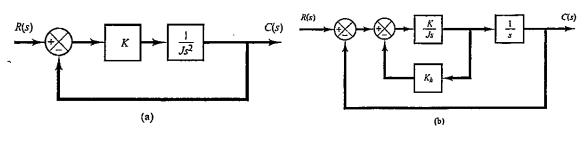


Figure. 5