國立高雄應用科技大學 101 學年度碩士班招生考試 電機工程系

准考證號碼□□□□□□□□□ (考生必須填寫)

控制系統 (乙組)

試題 共2頁,第1頁

注意:a. 本試題共 5 題, 每題 20 分, 共 100 分。

- b. 作答時不必抄題。
- C. 考生作答前請詳閱答案卷之考生注意事項。
- 1. For a controlled unity feedback system with forward transfer function:

$$G_c(s)G_p(s) = \frac{k(s+2)}{s+20} \frac{1}{s(s-1)}$$

Sketch its root locus and find the range of k for which the system is stable.

2. For the system described by the equation:

$$\dot{x}(t) = \begin{bmatrix} 0 & 1 \\ -8 & -4 \end{bmatrix} x(t) + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u(t)$$

Design a state feedback gain matrix u(t) = -kx(t) so that:

- (a) New system has the closed-loop poles with damping coefficient $\xi = 0.707$
- (b) Its step response peak time $t_p \le 3.14 \text{ sec}$
- 3. For a discrete control system as follow:

$$x(k+1) = \begin{bmatrix} 0 & 1 \\ -0.16 & -1 \end{bmatrix} x(k) + \begin{bmatrix} 1 \\ 1 \end{bmatrix} u(k)$$
$$y(k) = \begin{bmatrix} 1 & 0 \end{bmatrix} x(k) \qquad x(0) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

- (a) Prove that the system is stable
- (b) Find its state transition matrix
- (c) If u(k) = 0, find its steady state output $y(\infty)$

4. Assume the transfer function of a linear control system is:

$$\frac{Y(s)}{R(s)} = \frac{s + \alpha}{s^3 + 7s^2 + 14s + 8}$$

- (a). Determine α so that the system is either uncontrollable or unobservable
- (b). With the value of α found in (a), define the system state variable and write its state equation so that one of the states is uncontrollable
- 5. A negative unity feedback system has the forward path transfer function:

$$G(s) = \frac{100e^{-T_d s}}{s(s^2 + 10s + 100)}$$
 where T_d is the time delay in sec

- (a) If $T_d = 0$, what is the phase margin(PM) of this system
- (b) If $T_d \neq 0$, determine the maximum time delay T_d allowed for the closed loop system to be stable