

科目	控制系統	適用系所	自動控制工程學系	時間	100 分鐘
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※請務必在答案卷作答區內作答。

共 2 頁第 1 頁

1. Consider an open-loop system shown in Fig. 1.

- (a) When  $R(s) = \frac{4}{s^2+4}$  and  $y_{ss}(t) = \sqrt{5} \sin(\omega t + \theta)$ , find  $k$ ,  $\omega$  and  $\theta$ . (5%)
- (b) Define  $M(s) = \frac{G(s)}{1+G(s)}$ , where  $G(s) = \frac{k}{(s+2)(s+5)}$ , find  $k$  such that the poles of  $M(s)$  have damping ratio  $\zeta = 0.5$ . (5%)
- (c) Find the band-width (B.W.) of the system. (5%)
- (d) Find resonant peak  $M_r$  and resonant frequency  $\omega_r$ . (5%)

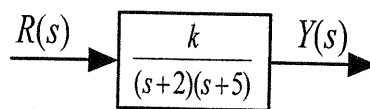


Fig. 1

2. Consider one unity negative feedback control system with open-loop transfer function:

$$G(s) = \frac{k(s+10)}{s(s+1)(s+5)}$$

- (a) Find the value of  $k$  such that the closed-loop system has gain margin G.M. = 6dB. (5%)
- (b) Find the value of  $k$  such that the closed-loop system has phase margin P.M. = 30°. (5%)
3. Consider the control system shown in Fig. 2. Suppose that the system has poles  $s = -1 \pm \sqrt{3}j$ .
- (a) Find the values of  $k$  and  $a$ . (5%)
- (b) When  $r(t) = 1 + 2t$ , calculate the  $e_{ss}(t)$ . (5%)

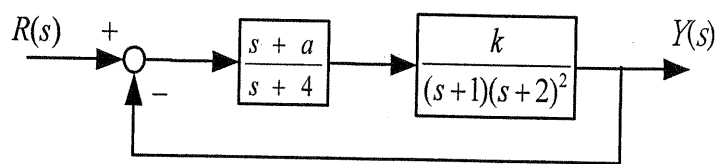


Fig. 2

4. Consider the control system shown in Fig. 3. Sketch the root-locus of the closed-loop system with  $k > 0$ .

(10%)

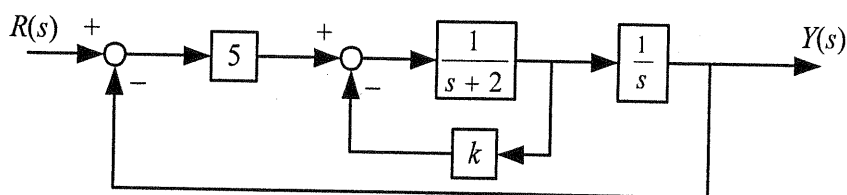


Fig. 3

5. Consider the network shown in Fig. 4.

- (a) Find the state equation of the network.

(5%)

- (b) Find the equilibrium state of the system. (5%)  
 (c) Is the equilibrium state asymptotically stable? (5%)

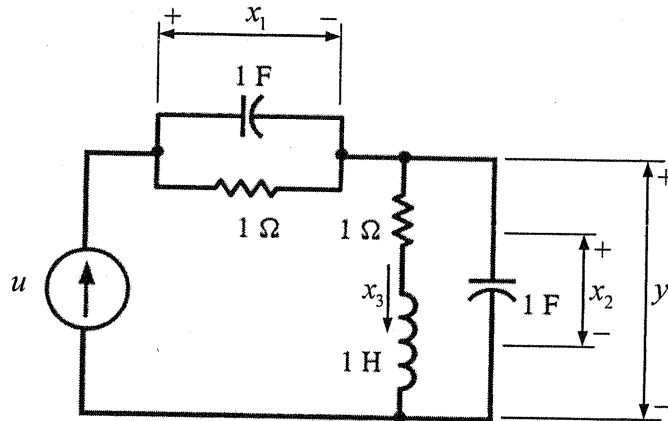


Fig. 4

6. Consider the following dynamic system:

$$4\ddot{y} + 32\dot{y} + 60y = 3\dot{u} + 2u$$

Determine the transfer function  $M(s)$  such that the unit-step response of  $M(s)$  is equivalent to the free response of  $y(t)$  for the initial conditions  $y(0) = 4$  and  $\dot{y}(0) = 0$ . (10%)

7. Consider the following state equation:

$$\dot{\mathbf{x}} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -3 & -3 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} u$$

$$y = [1 \quad 2 \quad 1] \mathbf{x}$$

- (a) Is the system controllable? (5%)  
 (b) Is the system observable? (5%)

8. Consider the network shown in Fig. 5.

- (a) Find the transfer function of the network. (5%)  
 (b) Is it BIBO stable? (5%)  
 (c) Find the output response  $y(t)$  if the input is  $u(t) = \sin t$ . (5%)

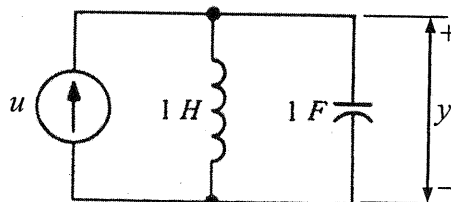


Fig. 5