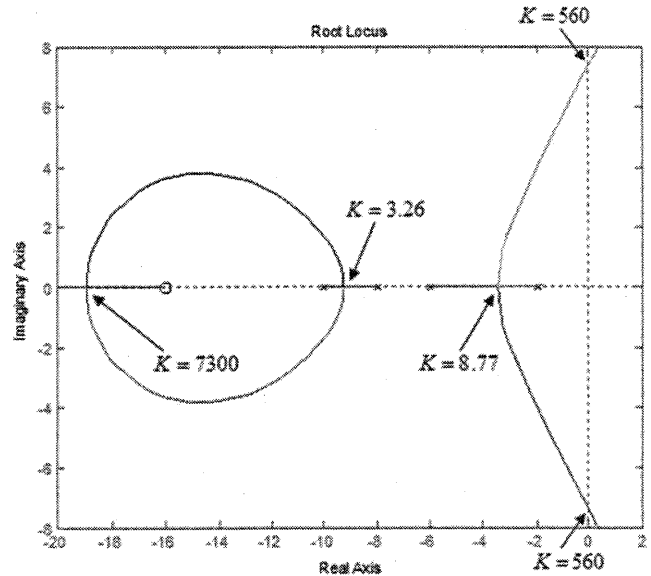


科目	自動控制	適用系所	航太與系統工程學系控制組	時間	100 分鐘
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※請務必在答案卷作答區內作答。 共 2 頁第 1 頁

- (20 %) Answer the following questions from the root locus diagram shown on the right
  - What is the approximate Characteristic Eq. for this plot(Hint: C.E.:  $D(s) + K N(s) = 0$ )?
  - What is the range of K that gives the stable system response?
  - What is the range of K that gives the stable and under-damped system response?
  - What is the value of K that gives the fastest system response?



- (20 %) The Routh-Hurwitz Criteria method.
  - Find the range of K values for which the following system will be stable.
 
$$S^3 + (2K - 26)S^2 + (100 - 14K)S + 4 = 0$$
  - Find the range of K values for which the following system will be stable.
 
$$S^3 + 9S^2 + 26S + K = 0$$

- (10 %) Determine the condition on  $b_1$ ,  $b_2$ ,  $c_1$  and  $c_2$  so that the following system is completely controllable & observable.

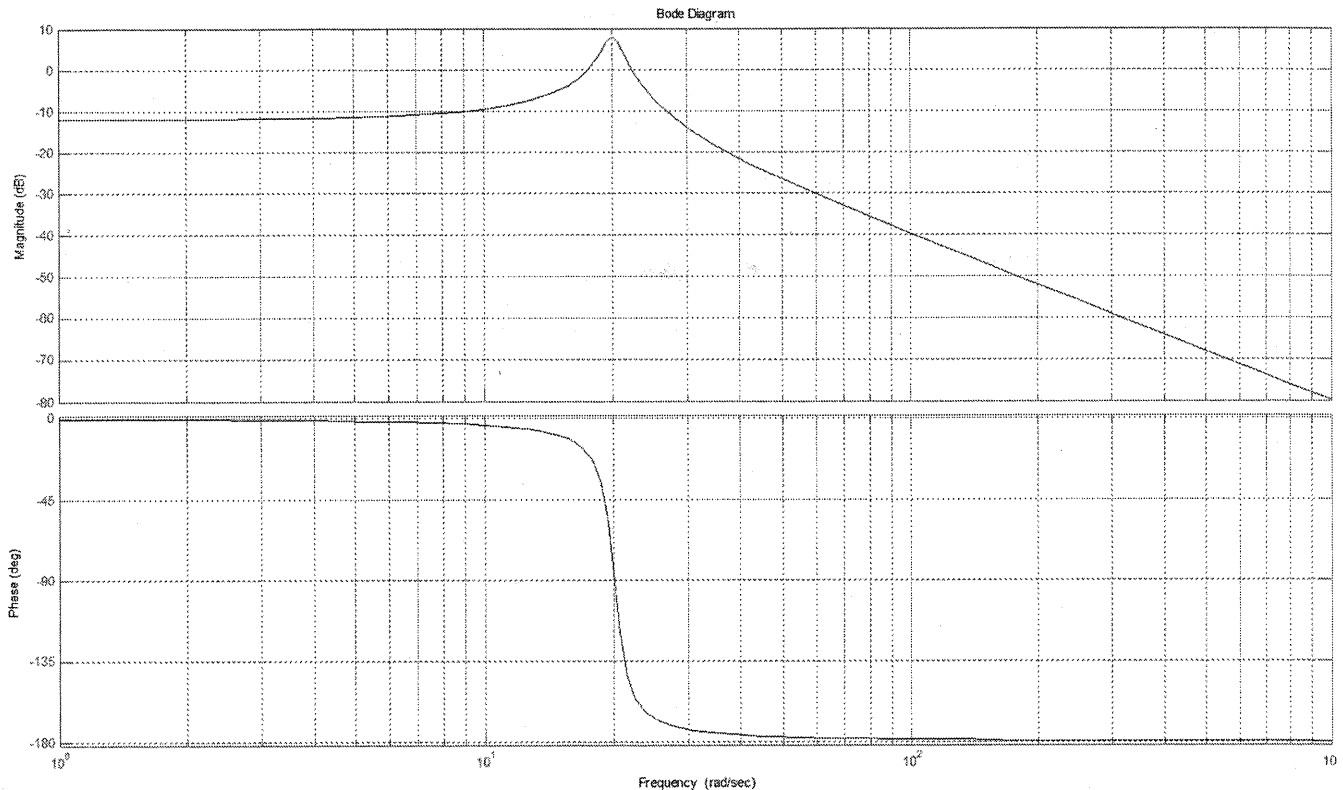
$$\frac{dx(t)}{dt} = Ax(t) + Bu(t) ; y(t) = Cx(t)$$

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \quad B = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \quad C = [c_1 \quad c_2]$$

- (10 %) Reduce the closed-loop transfer function of the system given below to 2<sup>nd</sup> order, and verify you result by using the Final Value Theorem with unit step input.

$$\frac{Y(s)}{R(s)} = \frac{600}{(s^2 + 22s + 120)(s^2 + 6s + 25)}$$

5. (20 %) Answer the following questions based on the Bode plot shown below:



(a) What is the approximate Transfer Function of above system:

(A)  $TF = \frac{S + a}{S^2 + 2\zeta\omega_n S + \omega_n^2}$  (B)  $TF = \frac{a}{S^2 + 2\zeta\omega_n S + \omega_n^2}$   
 (C)  $TF = \frac{1}{(S + a)(S^2 + 2\zeta\omega_n S + \omega_n^2)}$  (D)  $TF = \frac{aS}{S^2 + 2\zeta\omega_n S + \omega_n^2}$

- (b) What is the approximate value of constant a : (A) 1 (B) 10 (C) 100 (D) 1000.  
 (c) What is the approximate value of natural frequency  $\omega_n$  : (A) 2 (B) 10 (C) 11 (D) 20.  
 (d) What is the approximate value of damping ratio  $\zeta$  : (A) 0.5 (B) 0.05 (C) 0.2 (D) 0.707.

6. (20 %) Assume that a mass-spring-damper system is modeled by:  $\ddot{x} + 2\dot{x} + K_m x = f(t)$ ,

where  $x(t)$  is the position of the mass. If  $f(t) = 0$ , and the mass is held motionless

[i.e.,  $\dot{x}(0) = 0$ ] at  $x(0) = 5$  before being released at  $t = 0$ .

- (a) Determine the Characteristic Equation of this system.  
 (b) Find the value of  $K_m$  for the system to have the critical damped response.  
 (c) Find the range of  $K_m$  for the system to have the under damped response.  
 (d) Choose the value of  $K_m$  from the answer of (c) to have the time constant  $\tau = 2$ .